

A Skilled Algorithm for Performance Optimization of Distributed Computing System

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Abstract—*Distributed computing is an active area of research. Distributed Computing System (DCS) is becoming bigger and more complex. DCS consists different components and objects comprising an application which can be located on different computers connected to a network. In this paper we present an, considering DCS with heterogeneous processors in order to achieve optimal results for processing time, cost and reliability by allocating the tasks to the processors, in such a way that the allocated load on each processor is balanced. The present paper shows the functionalities of algorithm in terms of performance and time-complexity. A static task allocation policy is adopted in the present paper. A best allocation of tasks leads to a best balancing of the system. As in real life situation it is assumed that the number of tasks to be allocated is more than the number of processors.*

Index Terms— Processing Cost, Distributed Computing System (DCS), Processing Reliability, Task, Static.

I. INTRODUCTION

In Distributed Computing System (DCS), the term Distributed means to spread or Scattered or diffuse over a network [5, 18]. A DCS is a collection of independent computers linked by a computer network that appear to the users of the system as a single coherent system. There are several advantages of DCS such as reliability, incredibility growth, sharing of resources, flexibility, and speed. Distributed computing is essential in modern computing and communications systems. Examples are large-scale networks such as the Internet. A DCS consists of multiple autonomous machines that do not share primary memory, but cooperate by sending messages over a communication network. In any DCS task allocation [1, 8, 9] is an important and interesting problem. The term “task” can be defined as the smallest, identifiable and essential piece of a job that serves as a unit of work, and as a means of differentiating between the various components of any project. It is a function to be performed. Task allocation [12, 13, 14] refers to the way that tasks are chosen, assigned, and coordinated. It is the process that results in specific processors being engaged in specific tasks, in numbers appropriate to the available processors. Task allocation [19, 20, 21] can be static as well as dynamic. In the present paper the tasks are allocated statically because Static methods of task allocation [22, 24] have less overhead at run-time. In a static task allocation [16], the information regarding the tasks and processor attributes is assumed to be known in advance, before the execution of the tasks. The present algorithm in this paper shows the optimized results for

processing time, cost [2, 7] and reliability. Processing time is the time it takes to complete a prescribed procedure. Processing cost [17] is usually a monetary valuation of resources. Processing reliability is the ability of any system to consistently perform its intended or required functions, without degradation or failure. The key factor for any successful algorithm is to check the performance by calculating the time complexity and to compare it with other existing algorithms. Time complexity expresses the relationship between the size of the input and the run time for the algorithm. This paper presents a comparison of time complexity with other existing algorithm for measuring the performance with other existing algorithms. In this paper, we investigate the problem of static task allocation of concurrent programs for DCS with processor and resource heterogeneity.

II. OBJECTIVE

The prime objective of the present paper is to give an efficient algorithm to get the optimized results in terms of Processing time, processing cost and processing reliability in such a way that after processing the several steps the algorithm should show the minimum processing time, processing cost and high processing reliability. Our objective in the present research paper is also to achieve the results of the time complexity and to compare it with other algorithms which already exist for proving our algorithm better. Objective also includes that there must be the full advantage by taking the tasks statically in completing the work and to experiment the algorithm on different inputs for giving a skilled algorithm for achieving the technical aspects.

III. NOTATIONS

n : Number of Processors
m : Number of Tasks
c : Processing Cost
PTCRM : Processing Time cost Reliability Matrix
CM : Communication Matrix
UPTCRM : Updated Processing Time Cost Reliability Matrix
MPTCRM : Merged Processing Time Cost Reliability Matrix
PTM : Processing Time Matrix
CSPTM : Column Sum Processing Time Matrix
APT : Arranged Processing Time Matrix
PCM : Processing Cost Matrix
CSPCM : Column Sum Processing Cost Matrix
APCM : Arranged Processing Cost Matrix
PRM : Processing Reliability Matrix

CSPRM : Column Sum Processing Reliability Matrix
APRM : Arranged Processing Reliability Matrix
PTTAM : Processing Time Task Allocation Matrix
PCTAM : Processing Cost Task Allocation Matrix
PRTAM : Processing Reliability Task Allocation Matrix

IV. TECHNIQUE

In order to evaluate the overall optimal performance of a distributed network [15] we have chosen the problem where a set $P = \{p_1, p_2, p_3 \dots p_n\}$ of 'n' processors and a set $T = \{t_1, t_2, t_3 \dots t_m\}$ of 'm' tasks exists, where $m > n$. Every task contains some number of modules. For getting optimal processing time or processing cost or processing reliability for each task initially the emphasis will be on those modules of tasks which have the maximum probability of data transfer. Now, in case of time and cost the elements will be added and in case of reliability they will be multiplied. Now we have taken a matrix in which the time, cost and reliability of modules are defined and define a communication matrix by considering the communication between tasks. On the basis of highest communication we get a matrix namely MPTCRM (,,). Now from MPTCRM (,,) we can get the separate matrix for time, cost and reliability [3, 4]. Now in each matrix we will do the addition of each column and will rearrange the matrix in ascending order of their column sum. Negative and zero values will not be considered. For time and cost minimum value will be allocated and for reliability [6, 10] maximum value will be considered. Now the tasks can be allocated for getting the optimized results in terms of time, cost and reliability and Etime, Ecost and Ereliability is calculated. The function for obtaining the overall processing time [Etime], cost [Ecost], and reliability [Ereliability] is as follows- The function for obtaining the overall assignment time [Etime], cost [Ecost], and reliability [Ereliability] is as follows-

$$E_{time} = \left[\sum_{i=1}^n \left\{ \sum_{j=1}^n ET_{ij} X_{ij} \right\} \right] \quad (i)$$

$$E_{cost} = \left[\sum_{i=1}^n \left\{ \sum_{j=1}^n EC_{ij} X_{ij} \right\} \right] \quad (ii)$$

$$E_{reliability} = \left[\prod_{i=1}^n \left\{ \sum_{j=1}^n ER_{ij} X_{ij} \right\} \right] \quad (iii)$$

Where, $x_{ij} = \begin{cases} \geq 1, & \text{if } i^{\text{th}} \text{ task is assigned to } j^{\text{th}} \text{ processor} \\ 0, & \text{Otherwise} \end{cases}$

V. ALGORITHM

Step1: Start Algorithm
Step2: Read a set $T = \{t_1, t_2, t_3 \dots t_m\}$ of 'm' tasks.
Step3: Read a set $P = \{p_1, p_2, p_3 \dots p_n\}$ of 'n' processors.
Step4: Read the matrix PTCRM (,,). Select time/cost/reliability data corresponding to each task as needed of order $m * n$.

Step5: Input matrix CM (,,) by considering the communication time between modules of each task.
Step6: Consider each task on the basis of time or cost or reliability.
Step7: On the basis of Step 5 read the matrix UPTCRM (,,). This matrix will be derived from matrix PTCRM (,,).
Step8: Derived MPTCRM (,,) on the basis of process of merging the modules of tasks of highest communication.
Step9: From MPTCRM (,,) take the separate matrix for processing time, cost and reliability.
Step10: Compute sum of each column of PTM (,,), and store it into CSPTM (,,).
Step11: Arrange the CSPTM (,,) in ascending order of their column sum and store it into APTM (,,).
Step12: Compute addition of each column of PCM (,,) and store it into CSPCM (,,).
Step13: Arrange CSPCM (,,) in ascending order of their column sum and store it into APCM (,,).
Step14: Compute sum of each column of PRM (,,) and store it into CSPRM (,,).
Step15: Arrange the CSPRM (,,) in ascending order of their column sum and store it into APRM (,,).
Step16: While (all tasks! = allocated)

- (I). Select and allocate particular tasks from APTM (,,) on processors which has the minimal Processing time.
- (II). Select and allocate particular tasks from APCM (,,) on processors which has the minimal Processing cost.
- (III). Select and allocate particular tasks from APRM (,,) on processors which has the maximum Processing reliability.

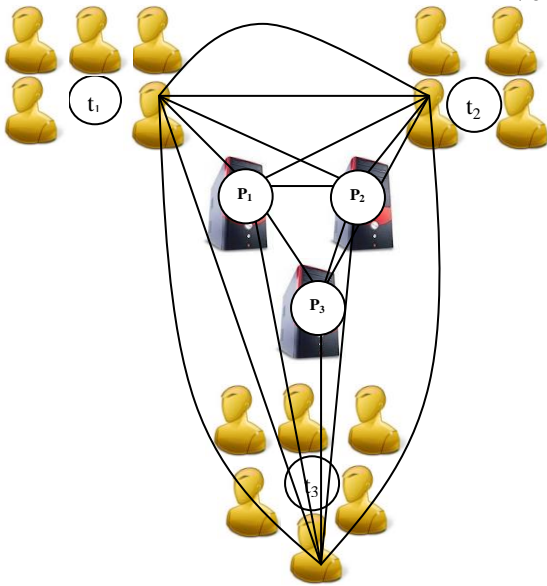
Step17: Compute the processor wise overall processing time, cost and reliability.

Step18: Display the result.

Step19: End of algorithm.

VI. IMPLEMENTATION

Let us consider a set of tasks T. This set consists three tasks t_1, t_2 , and t_3 . We may define it as, $T = \{t_1, t_2, t_3\}$. Now, consider the task t_1 has a set of task M_1 . This set consists the five modules. We may define it as, $M_1 = \{m_{11}, m_{12}, m_{13}, m_{14}, m_{15}\}$. Now, for task t_2 considers the set of task M_2 . This set consists the four modules. We may define it as, $M_2 = \{m_{21}, m_{22}, m_{23}, m_{24}\}$. Now, for task t_3 considers the set of task M_3 . This set consists the six modules. We may define it as, $M_3 = \{m_{31}, m_{32}, m_{33}, m_{34}, m_{35}, m_{36}\}$. The total number of processors are three and it can be define as, $P = \{p_1, p_2, p_3\}$. The processing time (t), cost (c) and reliability (r) of each module of every task on various processors are known and mentioned in the matrix namely, PTCRM (,,) of order $15 * 3$ which is given below-



$$\begin{bmatrix}
 & m_{21} & m_{22} & m_{23} & m_{24} \\
 m_{21} & 0 & 5 & 8 & 6 \\
 m_{22} & & 0 & 8 & 8 \\
 m_{23} & & & 0 & 7 \\
 m_{24} & & & & 0
 \end{bmatrix}$$

For task t_3 , the matrix CM (3,) of order 6*6 is as:

$$\begin{bmatrix}
 & m_{31} & m_{32} & m_{33} & m_{34} & m_{35} & m_{36} \\
 m_{31} & 0 & 4 & 7 & 2 & 1 & 5 \\
 m_{32} & & 0 & 8 & 9 & 8 & 3 \\
 m_{33} & & & 0 & 6 & 7 & 7 \\
 m_{34} & & & & 0 & 8 & 4 \\
 m_{35} & & & & & 0 & 9 \\
 m_{36} & & & & & & 0
 \end{bmatrix}$$

Processors		P_1	P_2	P_3
Tasks	Modules	t-c-r	t-c-r	t-c-r
t_1	m_{11}	160-2600-0.999232	180-2500-0.999332	170-2800-0.999420
	m_{12}	140-2100-0.999764	150-3000-0.999225	120-2800-0.999385
	m_{13}	130-2600-0.999123	110-2100-0.999223	130-2900-0.999784
	m_{14}	140-2800-0.999653	170-3000-0.999895	160-2400-0.999701
	m_{15}	150-2200-0.999111	110-2800-0.999327	100-2600-0.999785
t_2	m_{21}	180-3000-0.999980	150-2500-0.999329	200-2500-0.999772
	m_{22}	190-2400-0.999764	120-2900-0.999712	150-3000-0.999711
	m_{23}	160-2500-0.999555	170-2900-0.999222	155-2300-0.999806
	m_{24}	170-2800-0.999222	150-3000-0.999701	180-2100-0.999612
t_3	m_{31}	120-2000-0.999431	100-2700-0.999944	160-2500-0.999200
	m_{32}	140-2600-0.999711	175-2100-0.999288	180-2700-0.999405
	m_{33}	190-2700-0.999427	180-2500-0.999276	300-2900-0.999407
	m_{34}	160-2800-0.999908	200-2600-0.999275	210-2900-0.999500
	m_{35}	150-2900-0.999511	140-2900-0.999593	200-2700-0.999210
	m_{36}	200-2900-0.999450	110-2400-0.999282	130-2600-0.999228

Here it is considered that task t_1 is based on the constraint of execution time (one may choose the either cost or reliability constraint), task t_2 is based on the constraint of cost (one may choose the either time or reliability constraint), and task t_3 is based on the constraint of reliability (one may choose the either time or cost constraint). Hence, we can use the following form of data from matrix PTCRM (,) i.e. the execution time for task t_1 , execution cost for task t_2 , and execution reliability for task t_3 and can get the matrix namely UPTCRM (,) of order 15*3 in the following way-

Processors		P_1	P_2	P_3
Tasks	Modules	t-c-r	t-c-r	t-c-r
t_1	m_{11}	160-.....	180-.....	170-.....
	m_{12}	140-.....	150-.....	120-.....
	m_{13}	130-.....	110-.....	130-.....
	m_{14}	140-.....	170-.....	160-.....
	m_{15}	150-.....	110-.....	100-.....
t_2	m_{21}	...-3000-...	...-2500-...	...-2500-...
	m_{22}	...-2400-...	...-2900-...	...-3000-...
	m_{23}	...-2500-...	...-2900-...	...-2300-...
	m_{24}	...-2800-...	...-3000-...	...-2100-...
t_3	m_{31}	...-0.999431	...-0.999944	...-0.999200
	m_{32}	...-0.999711	...-0.999288	...-0.999405
	m_{33}	...-0.999427	...-0.999276	...-0.999407
	m_{34}	...-0.999908	...-0.999275	...-0.999500
	m_{35}	...-0.999511	...-0.999593	...-0.999210
	m_{36}	...-0.999450	...-0.999282	...-0.999228

The Considered Communication Time [23] Among The Modules Of Each Task Is Mentioned In The Matrices, Namely CM (,,).

For task t_1 , the matrix CM (1,) of order 5*5 is as:

$$\begin{bmatrix}
 & m_{11} & m_{12} & m_{13} & m_{14} & m_{15} \\
 m_{11} & 0 & 3 & 9 & 7 & 1 \\
 m_{12} & & 0 & 8 & 5 & 6 \\
 m_{13} & & & 0 & 3 & 5 \\
 m_{14} & & & & 0 & 4 \\
 m_{15} & & & & & 0
 \end{bmatrix}$$

For task t_2 , the matrix CM (2,) of order 4*4 is as:

Now, the task t_1 have five modules so on the basis of highest communication the modules m_{11} & m_{13} and m_{12} & m_{15} will be fused. The task t_2 have four modules so on the basis of highest communication the modules m_{21} & m_{23} will be fused. The task t_3 have six modules so on the basis of highest communication the modules m_{32} & m_{34} , m_{31} & m_{33} , m_{35} & m_{36} will be fused. The

resulting matrix namely MPTCRM (,) of order 9*3 will be as given below-

Processors		p ₁	p ₂	p ₃
Tasks	Modules	t-c-r	t-c-r	t-c-r
	m ₁₁ *m ₁₃	290	290	300
t ₁	m ₁₂ *m ₁₅	290	260	220
	m ₁₄	140	170	160
t ₂	m ₂₁ *m ₂₃	5500	3400	4800
	m ₂₂	2400	2900	3000
	m ₂₄	2800	3000	2100
t ₃	m ₃₂ *m ₃₄	0.999619	0.998563	0.998905
	m ₃₁ *m ₃₃	0.998858	0.999220	0.998607
	m ₃₅ *m ₃₆	0.998961	0.998875	0.998438

Now, from the MPCTR (,) matrix we can get three matrix namely PTM (,) of order 3*3, PCM (,) of order 3*3 and PRM(,) of order 3*3 which are given below-

		m ₁₁ *m ₁₃	m ₁₂ *m ₁₅	m ₁₄
PTM (,) =	p ₁	290	290	140
	p ₂	290	260	170
	p ₃	300	220	160

		m ₂₁ *m ₂₃	m ₂₂	m ₂₄
PCM (,) =	p ₁	5500	2400	2800
	p ₂	3400	2900	3000
	p ₃	4800	3000	2100

		m ₃₂ *m ₃₄	m ₃₁ *m ₃₃	m ₃₅ *m ₃₆
PRM (,) =	p ₁	0.999619	0.998858	0.998961
	p ₂	0.998563	0.999220	0.998875
	p ₃	0.998905	0.998607	0.998438

Now for PTM (,), which is for time factor, we will take the sum of each column which is given below in CSPTM (,) of order 4*3.

		m ₁₁ *m ₁₃	m ₁₂ *m ₁₅	m ₁₄
CSPTM(,) =	p ₁	290	290	140
	p ₂	290	290	170
	p ₃	300	220	160
	Σ	880	770	470

On making CSPTM (,), in ascending order of their column sum we get APTM (,) of order 4*3 which is given below-

		m ₁₄	m ₁₂ *m ₁₅	m ₁₁ *m ₁₃
APTM(,) =	p ₁	140	290	290
	p ₂	170	260	290
	p ₃	160	220	300
	Σ	470	770	880

On selecting tasks which have the minimal processing time at any specified Processor, we find the allocations which are mentioned below in PTTAM (,). Idle processor will be given the preference first.

	Processor	Allocated tasks	Processing time
PTTAM (,) =	p ₁	m ₁₄	140
	p ₂	m ₁₁ *m ₁₃	290
	p ₃	m ₁₂ *m ₁₅	220

The graphical representation is shown of PTTAM (,) is shown in figure: 2 which is given below-

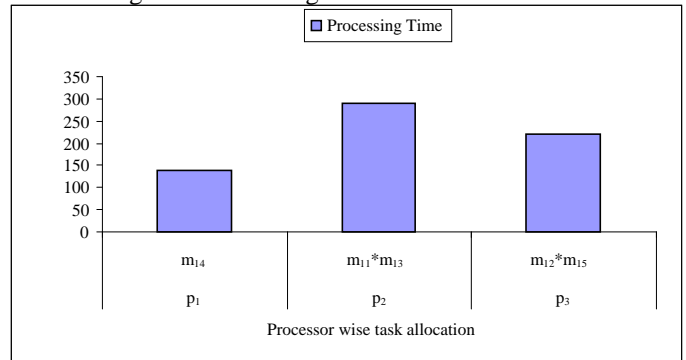


Fig 2: Processing Time task allocation

Now for PCM (,), which is for cost factor, same as above we will take the sum of each column which is given below in CSPCM (,) of order 4*3.

		m ₂₁ *m ₂₃	m ₂₂	m ₂₄
CSPCM (,) =	p ₁	5500	2400	2800
	p ₂	3400	2900	3000
	p ₃	4800	3000	2100
	Σ	13700	8300	7900

On making CSPCM (,), in ascending order of their column sum we get APCM (,) of order 4*3 which is given below-

		m ₂₄	m ₂₂	m ₂₁ *m ₂₃
APCM (,) =	p ₁	2800	2400	5500
	p ₂	3000	2900	3400
	p ₃	2100	3000	4800
	Σ	7900	8300	13700

On selecting tasks which have the minimal processing time at any specified Processor, we find the allocations which are

mentioned below in PCTAM (,), idle processor will be given the preference first.

	Processor	Allocated tasks	Processing cost
PCTAM (,,) =	p ₁	m ₂₂	2400
	p ₂	m ₂₁ *m ₂₃	3400
	p ₃	m ₂₄	2100

The graphical representation is shown of PCTAM (,,) is shown in figure: 3 which is given below-

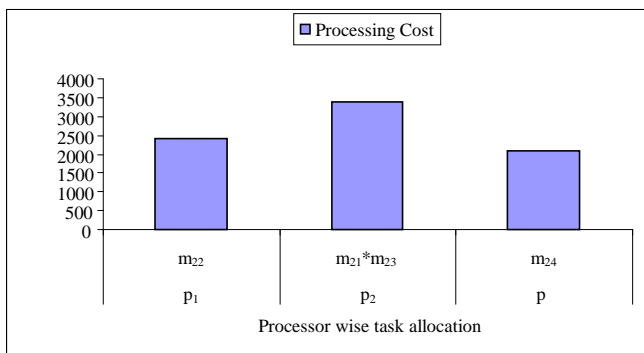


Fig 3: Processing Cost Task Allocation

Now for PRM (,,), which is for reliability factor, same as above we will take the sum of each column which is given below in CSPRM(,,) of order 4*3-

		m ₃₂ *m ₃₄	m ₃₁ *m ₃₃	m ₃₅ *m ₃₆
CSPRM(,,) =	p ₁	0.999619	0.998858	0.998961
	p ₂	0.998563	0.999220	0.998875
	p ₃	0.998905	0.998607	0.998438
	∏	0.997089	0.996688	0.996278

On making CSPRM (,,), in ascending order of their column sum we get APRM (,,) of order 4*3 which is given below-

		m ₃₂ *m ₃₄	m ₃₁ *m ₃₃	m ₃₅ *m ₃₆
APRM(,,) =	p ₁	0.999619	0.998858	0.998961
	p ₂	0.998563	0.999220	0.998875
	p ₃	0.998905	0.998607	0.998438
	∏	0.997089	0.996688	0.996278

On selecting tasks which have the maximal processing reliability at any specified Processor, we find the allocations which are mentioned below in PRTAM (,,), idle processor will be given the preference first.

	Processor	Allocated tasks	Processing reliability
PRTAM (,,) =	p ₁	m ₃₂ *m ₃₄	0.999619
	p ₂	m ₃₁ *m ₃₃	0.999220
	p ₃	m ₃₅ *m ₃₆	0.998438

The graphical representation is shown of PRTAM (,,) is shown in figure: 4 which is given below-

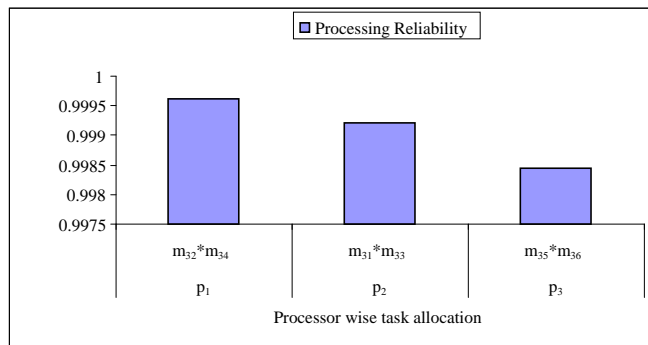


Fig 4: Processing Reliability Task Allocation

Now, From PTTAM (,) the overall processing time can be given by the following way-

Processors	Task allocation	Processing time
p ₁	m ₁₄	140
p ₂	m ₁₁ *m ₁₃	290
p ₃	m ₁₂ *m ₁₅	220

Overall Processing Time : 650

From PCTAM (,,) the overall processing cost can be given by the following way-

Processors	Task allocation	Processing Cost
p ₁	m ₂₂	2400
p ₂	m ₂₁ *m ₂₃	3400
p ₃	m ₂₄	2100

Overall Processing Cost : 7900

From PRTAM (,,) the overall processing reliability can be given by the following way-

Processor	Task allocation	Processing reliability
p ₁	m ₃₂ *m ₃₄	0.999619
p ₂	m ₃₁ *m ₃₃	0.999220
p ₃	m ₃₅ *m ₃₆	0.998438

Overall Processing Reliability : 0.997279

V. CONCLUSION

From the above results for overall processing time, processing cost and processing reliability the conclusion can be present in a tabular form for optimal Etime, Ecost and Ereliability which is given below-

Tasks	Processors			Optimal	Optimal	Optimal
	p ₁	p ₂	p ₃	Etime	Ecost	Ereliability
t ₁	m ₁₄	m ₁₁ *m ₁₃	m ₁₂ *m ₁₅	650
t ₂	m ₂₂	m ₂₁ *m ₂₃	m ₂₄	...	7900	...
t ₃	m ₃₂ *m ₃₄	m ₃₁ *m ₃₃	m ₃₅ *m ₃₆	0.997279

The analysis of any algorithm [11] specifically emphasis on

time complexity. The time complexity is a measure of the amount of time required to execute an algorithm. Time complexity expresses the relationship between the size of the input and the run time for the algorithm. It is a function of input size 'n'. The time complexity of the above mentioned algorithm is $O(mn)$. By taking several input examples, the above algorithm gives the results mentioned below-

No.of Processors(n)	No.of Tasks(m)	Optimal Results
3	4	12
3	5	15
3	6	18
3	7	21
4	5	20
4	6	24
4	7	28
4	8	32
5	6	30
5	7	35
5	8	40
5	9	45

The graphical representation of the above results are shown by figure 5, 6, and 7 as given below-

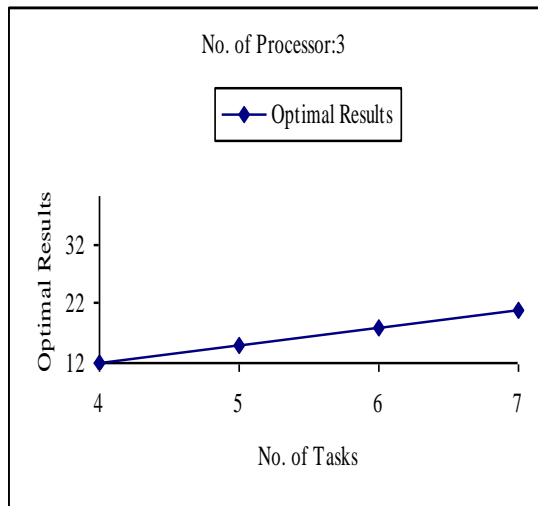


FIG 5: Processor Wise Complexity

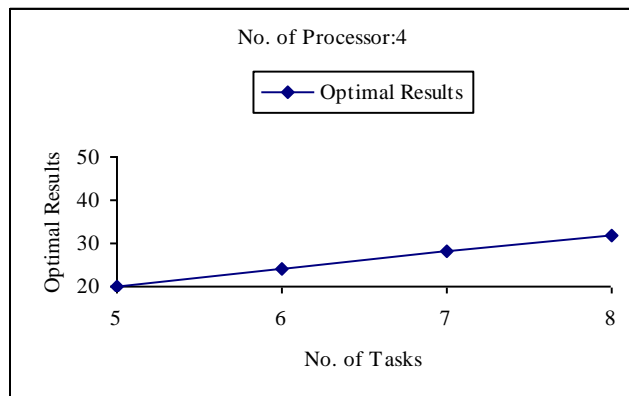


FIG 6: Processor wise Complexity

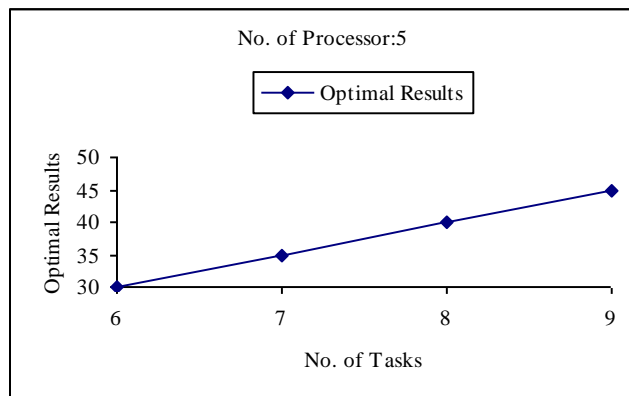


FIG 7: Processor Wise Complexity

The performance of the suggested algorithm is compared with the algorithm suggested by algorithm [23] as the given table shows the comparison of time complexity between algorithm [23] and presented algorithm-

Processor(n)	Tasks(m)	Time Complexity of algorithm[12] $O(mn^3 \log n)$	time complexity of present algorithm $O(mn)$
3	4	51	12
3	5	64	15
3	6	77	18
3	7	90	21
4	5	192	20
4	6	231	24
4	7	269	28
4	8	308	32
5	6	524	30
5	7	611	35
5	8	699	40
5	9	786	45

From the above table it is clear that algorithm proposed by us is much better for the optimal allocation of tasks for enhancing the performance of distributed computing system. The graphical representation is given below between algorithm [23] and present algorithm by figure 8, 9, and 10-

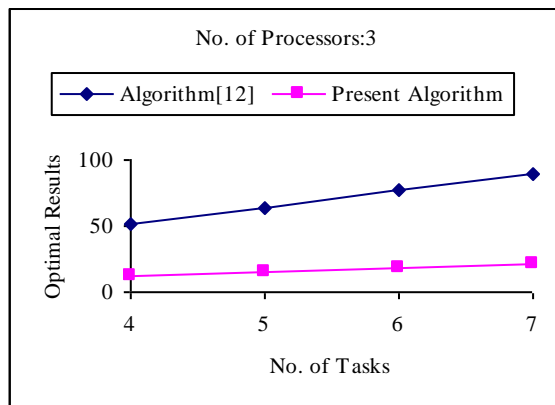


Fig 8: Comparison Graph

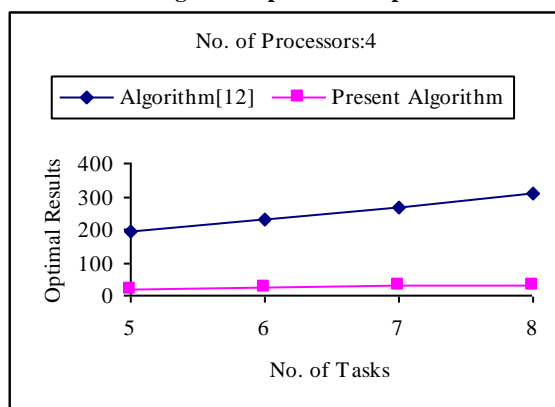


Fig 9: Comparison Graph

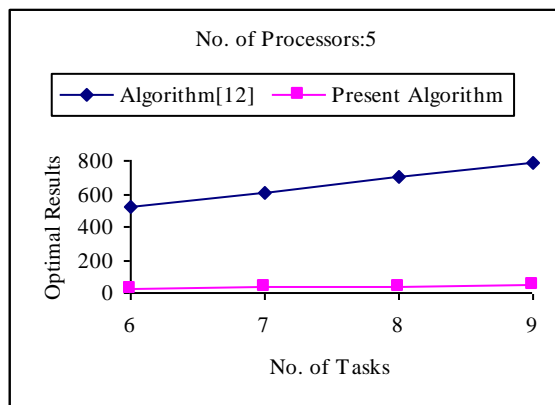


Fig 10: Comparison Graph

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